# Local Search and the Traveling Salesman Problem: A Feature-Based Characterization of Problem Hardness

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#### The Traveling Salesman Problem (TSP)



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# Aim: Predict Hardness of TSP instances

# Problem Hardness: Two options

## Number of swaps/iterations/...

Used in Smith-Miles et al. (2010)

# **Approximation quality**

Expected solution tour length

Optimal tour length

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#### **Characterize TSP instances**

## Requirement

All features can be computed without knowledge of the optimal tour. Eliminates some (interesting) features.

# Challenges

Normalization, dependence on # of nodes / edges

#### **Characterize TSP instances**

Taken from literature

#### Literature used

Smith-Miles et al. (2010), Kanda et al. (2011) and Smith-Miles and van Hemert (2011)

## **Classes of features**

- Nearest Neighbor Distance (NNDs)
- ▷ Clustering
- Edge Costs / Distance Matrix

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# Focus on 2-opt (Croes, 1958) algorithm.

#### Reasons

- Historically first successful local search method for TSP
- ▷ Easy to understand
- Some progress on theoretical analysis
   (Chandra et al., 1999 and Englert et al., 2007)

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# Where do the TSP instances come from?

#### **Instance Generator: EA**

```
function tsp_generator(popSize=30, instSize=100, poolSize=50,
                      digits=2, repetitions=500):
pop = randomInstances(popSize, instSize)
while not done:
  fitness = computeFitness(pop, repetitions)
  matingPool = tournamentSelection(pop, poolSize, fitness)
  nextPop[1] = pop[whichBest(fitness)]
  for k = 2 to popSize:
    parent1, parent2 = randomElements(2, matingPool)
     offspring = uniformCrossover(parent1, parent2)
    nextPop[k] = round(
       uniformMutation(normalMutation(offspring)), digits)
  pop = nextPop
```

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# Use EA to generate 100 easy and hard instances

# Problems

- Fitness function expensive
- Lots of manual tuning of EA
- Some runs hung

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#### Observation



1 Tour leg lengths differ less for hard instances.

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# Prediction

- Calculate all features for the 200 instances
- Use decision tree (CART) to predict instance type

10-fold CV error rate: 3.02%

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# This was an ``easy" task. Instances chosen to be maximally different!

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We are missing instances that are between the two classes.

#### Idea

Create convex combination of an easy  $I_e$  and a hard instance  $I_h$  $I_n = \alpha I_e + (1 - \alpha) I_h \quad \text{with} \quad \alpha \in [0, 1]$ 

#### **Possible Improvements**

Match up points to minimize movement

#### Usage

- For every combination of instances generate morph
- $\triangleright$  Calculate features for different  $\alpha$  (0.2, 0.4, ..., 0.8)

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# **Problem Hardness**



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## Max Edge Cost



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# CoV of nNNDs



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Mean of nNNDs



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Variation of Edge Cost



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#### **Ratio of Cities near Edge**



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# Prediction

Fit MARS model to data.

- Only use subset of morph results
- Do SFS to select subset of variables

## RMSE estimated via 3-fold CV: 0.0113

## Interpretation

Not a black-box model. Please see paper for plots and interpretation.

# Conclusion

- Generated ``easy" and ``hard" instances for 2-opt heuristic
- Characterized the instance sets using easily calculated features
- Showed novel approach to generate ``medium" instances (morphing)
- Predicted hardness of instance based on features using simple models

# Outlook

- Optimize instance generation
- Study relation between features and theoretical properties of 2-opt
- Improve morphing
- Generate more diverse instance sets



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